

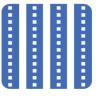
Politecnico di Torino Interdepartmental Centre for Service Robotics

Marcello Chiaberge

marcello.chiaberge@polito.it

Centre Coordinator





SMART CITY SEARCH & RESCUE



SERVICE ROBOTICS FOR WELLBEING



CULTURAL HERITAGE



UNDERWATER



SPACE



PIC4SeR - Service robotics

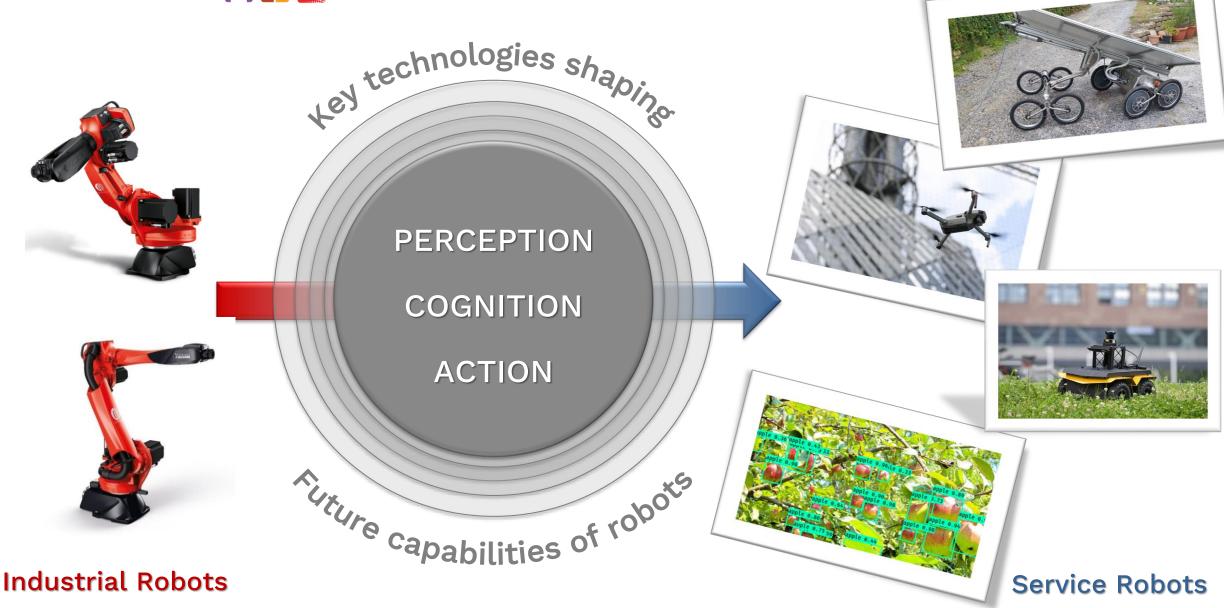
Service robots assist human beings, typically by performing a job that is dirty, dull, distant, dangerous or repetitive, including household-chores. They typically are autonomous and/or operated by a built-in control system, with manual override options. The term "service robot" does not have a strict technical definition. The International Organization for Standardization defines a "service robot" as a robot "that performs useful tasks for humans or equipment excluding industrial automation applications"







PIC4SeR - Service robotics



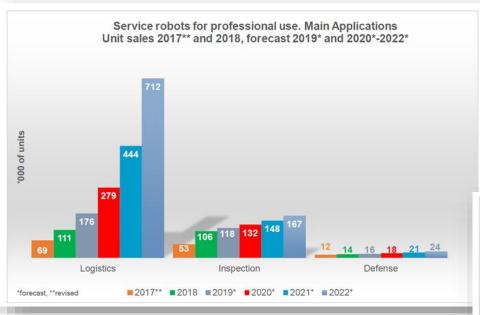


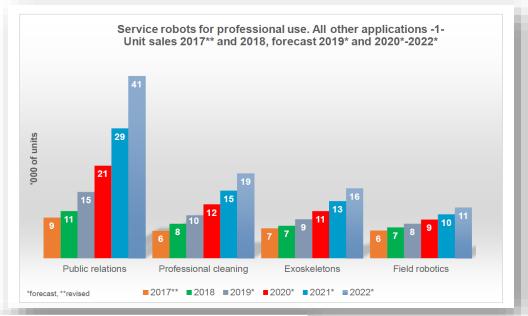


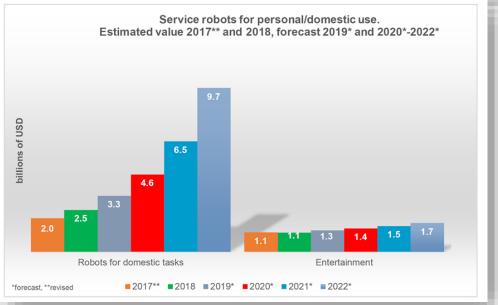


PIC4SeR - Reference market

IFR (International Federation of Robotics) "World Robotics 2019 – Service Robots"













PIC4SeR - Why?

- Many of the current research, innovation and development in the service robotic field, can be classified as disruptive technologies
- Several uncorrelated research projects and industrial partnerships must be harmonized and coordinated to optimize the results
- To start a common workplace, a common knowledge and a common language
- To develop an integrated approach and technology development process in this booming area
- To help PoliTO reaching a critical mass in this sector (instead of several scattered initiatives)
- To link together technology needs coming from several industrial partners
- To start interdisciplinary didactic activities in this area
- To join several international research communities with a unique "face" and coordinated research proposals









PIC4SeR in pills

5 PoliTO departments

- DET (Electronics & Telecoms)
- DAUIN (Informatics & Control)
- **DIMEAS (Mechanics & Aerospace)**
- DIATI (Geomatics & Photogrammetry)
- DAD (Design & Cultural Heritage)

50 people involved

- 21 staff
- 12 researcher
- 17 PhD students

Location: c/o COVIVIO building

- C.so Ferrucci 112 Torino
- 580mq of labs and offices
- indoor & outdoor facilities available for testing







PIC4SeR - Enabling technologies

GNSS navigation /Energy optimization 4G and 5G Networks Cooperative positioning /Path planning **Sensor** integration **SDR** receivers Soft robotics **Locomotion** platforms /Multimedia communication ROS2 **Control Coding Human Machine Interaction** Internet of Things **Machine Learning** Interaction visualitazion **Artificial Intelligence** Data fusion Interaction design /System Co-Design /Edge-Fog-Cloud Computing **Ethics** Co-living Design **Embedded** Computing







PIC4SeR – key application areas











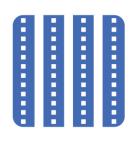




PIC4SeR – key application areas







SMART CITY SEARCH & RESCUE









PIC4SeR – key application areas















PIC4SeR – Internal organization

	PLATFORMS			TECHNOLOGIES			
Projects Applications	UGV	UAV	AUV & ROV	AI & ML	Local/Global Positioning	Mechanism design	Electronics & Control
	Core	Core	Core	Generalization	GNSS	Locomotion platforms	Energy management
	SLAM	SLAM	Navigation	Perception (CV)			Embedded systems
	Planning	Planning	Planning	Vision / Image processing	UWB	Robotic arms	System architecture
	Indoor/ Outdoor			Edge AI			Power electronics







Companies & Research partners























European Space Agency



























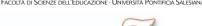


































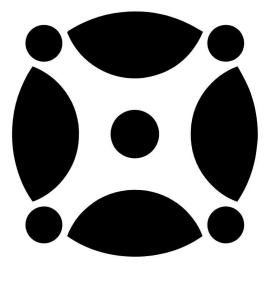
SCAN ME

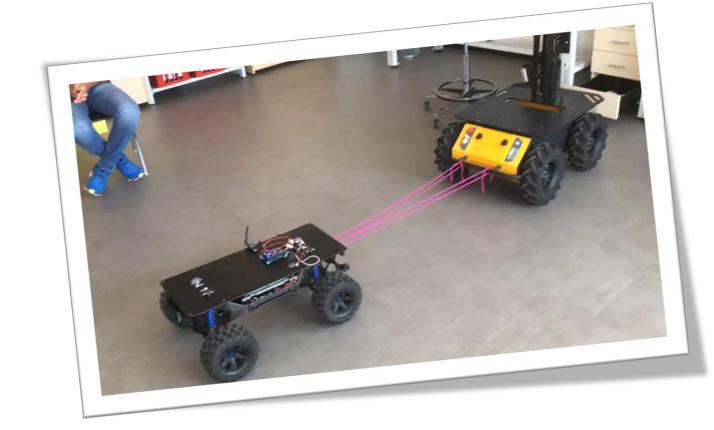






Thank you





www.pic4ser.polito.it